

MINKOWSKI VALUATIONS

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ABSTRACT. Centroid and difference bodies define $SL(n)$ equivariant operators on convex bodies and these operators are valuations with respect to Minkowski addition. We derive a classification of $SL(n)$ equivariant Minkowski valuations and give a characterization of these operators. We also derive a classification of $SL(n)$ contravariant Minkowski valuations and of L_p -Minkowski valuations.

Centroid, difference, and projection bodies are fundamental notions in the affine geometry of convex bodies. The most important affine isoperimetric inequalities (and open problems) are formulated using these bodies. We show that the operators defined by these bodies together with the identity are basically the only examples of homogeneous, $SL(n)$ equivariant or contravariant Minkowski valuations.

The centroid body ΓK of a convex body $K \subset \mathbb{R}^n$ is a classical notion from geometry (see [5], [16], [36]) that has attracted much attention in recent years (see [4], [6], [8], [20], [21], [25], [27], [31]). If K is α -symmetric, then ΓK is the body whose boundary consists of the locus of the centroids of the halves of K formed when K is cut by hyperplanes through the origin. In general it can be defined in the following way. Let \mathcal{K}^n denote the set of convex bodies (that is, of compact, convex sets) in \mathbb{R}^n , and let \mathcal{K}_o^n denote the set of convex bodies in \mathbb{R}^n that contain the origin. A convex body K is uniquely determined by its support function $h(K, \cdot)$, where $h(K, v) = \max\{v \cdot x : x \in K\}$, $v \in \mathbb{R}^n$, and where $v \cdot x$ denotes the standard inner product of v and x . The *moment body* MK of $K \in \mathcal{K}_o^n$ is the convex body whose support function is given by

$$h(MK, v) = \int_K |v \cdot x| dx.$$

If the n -dimensional volume $\text{vol}_n(K)$ of K is positive, then the *centroid body* ΓK of K is defined by

$$\Gamma K = \frac{1}{\text{vol}_n(K)} MK.$$

The fundamental affine isoperimetric inequality for centroid bodies is the Busemann-Petty centroid inequality [32]: Among bodies of given volume precisely for centered ellipsoids the centroid bodies have minimal volume. It is one of the major open problems to determine the reverse inequality (see [31]).

The *difference body* DK of $K \in \mathcal{K}_o^n$ is the Minkowski (or vector) sum of K and its reflection in the origin, that is,

$$DK = K + (-K).$$

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The operation that forms the difference body is essentially that known as central symmetrization and as such finds many applications in geometry and mathematical physics. The fundamental affine isoperimetric inequality for difference bodies is the Rogers-Shephard inequality [34]: Among bodies of given volume precisely for simplices the difference bodies have maximal volume.

The moment and difference operators are both Minkowski valuations. Here an operator Z is called a *Minkowski valuation* if

$$Z K_1 + Z K_2 = Z(K_1 \cup K_2) + Z(K_1 \cap K_2),$$

whenever $K_1, K_2, K_1 \cup K_2 \in \mathcal{K}^n$ and addition on \mathcal{K}^n is Minkowski addition. Valuations on convex bodies are a classical concept. In 1900, Dehn used them for solving Hilbert's third problem on the non-equidecomposability of convex polytopes of equal volume in \mathbb{R}^3 . Probably the most famous result on valuations is Hadwiger's characterization of rigid motion invariant real valued valuations continuous with respect to the Hausdorff metric as linear combinations of quermassintegrals. See [9], [15], [29], [30] for information on the classical theory and [1]–[3], [11]–[14], [18], [19], [37] for some of the more recent results.

An operator $Z : \mathcal{K}^n \rightarrow \mathcal{K}^n$ is *Minkowski additive* if $Z(K_1 + K_2) = Z K_1 + Z K_2$ for $K_1, K_2 \in \mathcal{K}^n$. Note that every Minkowski additive operator is a Minkowski valuation but not vice versa. Continuous Minkowski additive operators that commute with rigid motions are called endomorphisms. Schneider [35] (see also [36]) showed that there is a great variety of these operators. He obtained a complete classification of endomorphisms in \mathcal{K}^2 and characterizations of special endomorphisms in \mathcal{K}^n . These results were further extended by Kiderlen [10].

We show that the moment and difference operators are basically the only examples of homogeneous, $\mathrm{SL}(n)$ equivariant Minkowski valuations. Here an operator $Z : \mathcal{K}_o^n \rightarrow \mathcal{K}^n$ is called *$\mathrm{SL}(n)$ equivariant*, if

$$Z(\phi K) = \phi Z K \quad \text{for } \phi \in \mathrm{SL}(n),$$

and it is called *homogeneous of degree r* , $r \in \mathbb{R}$, if

$$Z(s K) = s^r Z K \quad \text{for } s \geq 0.$$

Let \mathcal{P}_o^n denote the set of convex polytopes in \mathbb{R}^n that contain the origin. For $n \geq 3$, we show that $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$ is a homogeneous, $\mathrm{SL}(n)$ equivariant Minkowski valuation if and only if there are constants $c_0 \in \mathbb{R}$, $c_1, c_2 \geq 0$ such that

$$Z P = c_0 m(P) + c_1 M P \quad \text{or} \quad Z P = c_1 P + c_2(-P)$$

for every $P \in \mathcal{P}_o^n$, where $m(P)$ is the moment vector of P . In particular, this implies that these are all continuous, homogeneous, $\mathrm{SL}(n)$ equivariant Minkowski valuations on \mathcal{K}_o^n . Combined with McMullen's polynomial expansion for translation invariant valuations [28], it implies that $Z : \mathcal{P}^n \rightarrow \mathcal{K}^n$ is a translation invariant, $\mathrm{SL}(n)$ equivariant Minkowski valuation if and only if there is a constant $c \geq 0$ such that

$$Z P = c D P$$

for every $P \in \mathcal{P}^n$. We also derive the corresponding results in the context of the L_p -Brunn-Minkowski theory and give a characterization of L_p -centroid bodies.

The *projection body* ΠK of K is the convex body whose support function is given for $u \in S^{n-1}$ by

$$h(\Pi K, u) = \mathrm{vol}_{n-1}(K|u^\perp),$$

where vol_{n-1} denotes $(n-1)$ -dimensional volume and $K|u^\perp$ denotes the image of the orthogonal projection of K onto the subspace orthogonal to u . Projection bodies, which were introduced by Minkowski, are an important tool for studying projections (see [5]). In recent years, projection bodies and their generalizations in the L_p -Brunn-Minkowski theory have attracted increased attention; see [7], [25], [26], [39]. The fundamental affine isoperimetric inequalities for projection bodies are the Petty projection inequality [33] and the Zhang projection inequality [38]: Among bodies of given volume precisely for ellipsoids the polar projection bodies have maximal volume and precisely for simplices the polar projection bodies have minimal volume. It is a major open problem to determine the corresponding results for the volume of the projection body itself (see [23]).

We derive a classification of homogeneous, $\text{SL}(n)$ contravariant Minkowski valuations and give a characterization of the projection operator. Here an operator $Z : \mathcal{K}_o^n \rightarrow \mathcal{K}^n$ is called $\text{SL}(n)$ *contravariant*, if

$$Z(\phi K) = \phi^{-t} Z K \quad \text{for } \phi \in \text{SL}(n),$$

where ϕ^{-t} denotes the inverse of the transpose of ϕ . This classification generalizes a result in [17] where it is shown that an operator $Z : \mathcal{P}^n \rightarrow \mathcal{P}^n$ is a Minkowski valuation that is $\text{SL}(n)$ contravariant, translation invariant and homogeneous of degree $(n-1)$ if and only if it is a multiple of the projection operator. Here we obtain that an operator $Z : \mathcal{P}^n \rightarrow \mathcal{K}^n$ is a translation invariant, $\text{SL}(n)$ contravariant Minkowski valuation if and only if there is a constant $c \geq 0$ such that

$$Z P = c \Pi P$$

for every $P \in \mathcal{P}^n$. We also derive the corresponding results in the context of the L_p -Brunn-Minkowski theory.

1. EQUIVARIANT MINKOWSKI VALUATIONS

In this section, our main result on the classification of $\text{SL}(n)$ equivariant Minkowski valuations is formulated. The important examples are the difference operator, the moment operator and the moment vector. Here the moment vector $m(K)$ of a convex body $K \in \mathcal{K}_o^n$ is defined by

$$m(K) = \int_K x \, dx.$$

Note that the moment operator $M : \mathcal{K}_o^n \rightarrow \mathcal{K}^n$ and the moment vector $m : \mathcal{K}_o^n \rightarrow \mathbb{R}^n$ commute (up to a determinantal factor) with general linear transformations:

$$M(\phi K) = |\det \phi| \phi M K \quad \text{and} \quad m(\phi K) = |\det \phi| \phi m(K) \quad \text{for } \phi \in \text{GL}(n).$$

The difference operator and the identity are $\text{SL}(n)$ equivariant and homogeneous of degree 1. As we will see, for $n \geq 3$ these are already all examples of homogeneous, $\text{SL}(n)$ equivariant Minkowski valuations on \mathcal{P}_o^n .

For $n = 2$, we have an additional example. Let $\mathcal{E}_o(P)$ be the set of edges of P that contain the origin. For $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_i + b_0 + b_1, a_0 + a_1 + b_i \geq 0$, $i = 1, 2$, define $Z : \mathcal{P}_o^2 \rightarrow \mathcal{P}_o^2$ by

$$(1) \quad Z P = a_0 P + b_0(-P) + \sum (a_i E_i + b_i(-E_i)),$$

where the sum is taken over $E_i \in \mathcal{E}_o(P)$. Here and throughout formulae like (1) have to be read as

$$h(ZP, v) = a_0 h(P, v) + b_0 h(-P, v) + \sum (a_i h(E_i, v) + b_i h(-E_i, v))$$

for $v \in \mathbb{R}^2$. The notation is only used if $h(ZP, \cdot)$ is the support function of a convex body, which is here guaranteed by the conditions on a_i, b_i . Note that $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}^2$ defined by (1) is $\text{SL}(2)$ equivariant, homogeneous of degree 1, and Minkowski additive.

The following result is our classification of $\text{SL}(n)$ equivariant Minkowski valuations. The proof is given in Section 3.

Theorem 1. *Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$, $n \geq 3$, be a Minkowski valuation which is $\text{SL}(n)$ equivariant and homogeneous of degree r . If $r = n + 1$, then there are constants $a_0 \in \mathbb{R}$, $a_1 \geq 0$ such that*

$$ZP = a_0 m(P) + a_1 MP$$

for every $P \in \mathcal{P}_o^n$. If $r = 1$, then there are constants $a, b \geq 0$ such that

$$ZP = aP + b(-P)$$

for every $P \in \mathcal{P}_o^n$. In all other cases, $ZP = \{o\}$ for every $P \in \mathcal{P}_o^n$.

Let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}^2$ be a Minkowski valuation which is $\text{SL}(2)$ equivariant and homogeneous of degree r . If $r = 3$, then there are constants $a_0 \in \mathbb{R}$, $a_1 \geq 0$ such that

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for every $P \in \mathcal{P}_o^2$. If $r = 1$, then there are constants $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_i + b_0 + b_1, a_0 + a_1 + b_i \geq 0$, $i = 1, 2$, such that

$$ZP = a_0 P + b_0(-P) + \sum (a_i E_i + b_i(-E_i))$$

for every $P \in \mathcal{P}_o^2$, where the sum is taken over $E_i \in \mathcal{E}_o(P)$. In all other cases, $ZP = \{o\}$ for every $P \in \mathcal{P}_o^2$.

Let \mathcal{K}^n and \mathcal{K}_o^n be equipped with the topology defined by the Hausdorff metric. We have the following simple consequence of Theorem 1. Note that there are further examples of homogeneous, $\text{SL}(n)$ equivariant Minkowski valuations on \mathcal{K}_o^n that are not continuous (see [35]).

Corollary 1.1. *If $Z : \mathcal{K}_o^n \rightarrow \mathcal{K}^n$, $n \geq 2$, is a continuous, homogeneous, $\text{SL}(n)$ equivariant Minkowski valuation, then there are constants $a_0 \in \mathbb{R}$, $a_1, a_2 \geq 0$ such that*

$$ZK = a_0 m(K) + a_1 MK \quad \text{or} \quad ZK = a_1 K + a_2(-K)$$

for every $K \in \mathcal{K}_o^n$.

For translation invariant valuations, we obtain the following result.

Corollary 1.2. *If $Z : \mathcal{P}^n \rightarrow \mathcal{K}^n$, $n \geq 2$, is a translation invariant, $\text{SL}(n)$ equivariant Minkowski valuation, then there is a constant $c \geq 0$ such that $Z = cD$.*

Here an operator $Z : \mathcal{K}^n \rightarrow \mathcal{K}^n$ is called *translation invariant*, if $Z(K + x) = ZK$ for $x \in \mathbb{R}^n$. The proof of this corollary is given in Section 7.

2. EQUIVARIANT L_p -MINKOWSKI VALUATIONS

For $p > 1$, the L_p -Minkowski sum $K_1 +_p K_2$ of $K_1, K_2 \in \mathcal{K}_o^n$ is defined by

$$h^p(K_1 +_p K_2, v) = h^p(K_1, v) + h^p(K_2, v)$$

for $v \in \mathbb{R}^n$. This notion, which was introduced by Firey in the middle of the last century, is at the heart of the L_p -Brunn-Minkowski theory (or Brunn-Minkowski-Firey theory); see [22], [24]. We derive a classification of homogeneous, $\mathrm{SL}(n)$ equivariant L_p -Minkowski valuations. Here an operator $Z : \mathcal{K}_o^n \rightarrow \mathcal{K}_o^n$ is called an *L_p -Minkowski valuation* if

$$Z K_1 +_p Z K_2 = Z(K_1 \cup K_2) +_p Z(K_1 \cap K_2),$$

whenever $K_1, K_2, K_1 \cup K_2 \in \mathcal{K}_o^n$.

The important examples of $\mathrm{SL}(n)$ equivariant L_p -Minkowski valuations are the L_p -moment operator and the L_p -difference operator. These can be defined in the following way. For $-1 \leq \tau \leq 1$, define $M_p^\tau : \mathcal{K}_o^n \rightarrow \mathcal{K}_o^n$ by

$$h^p(M_p^\tau K, v) = \int_K (|v \cdot x| + \tau(v \cdot x))^p dx$$

for $v \in \mathbb{R}^n$. For $\tau = 0$, we obtain the *L_p -moment operator* M_p . If $\mathrm{vol}_n(K) > 0$, then the *L_p -centroid body* $\Gamma_p K$ of K is defined by

$$\Gamma_p K = \frac{c_{n,p}}{\mathrm{vol}_n(K)} M_p K,$$

where the constant $c_{n,p}$ is chosen such that $\Gamma_p B = B$ for the unit ball B . L_p -centroid bodies were introduced by Lutwak and Zhang [27], for $p = 2$ they are the Legendre ellipsoids of classical mechanics. Lutwak, Yang, and Zhang [25] obtained the L_p -version of the Busemann-Petty centroid inequality; see Campi and Gronchi [4] for a different proof. Note that

$$M_p^\tau(\phi K) = |\det \phi|^{1/p} \phi M_p^\tau K \quad \text{for } \phi \in \mathrm{GL}(n),$$

and that M_p^τ is an L_p -Minkowski valuation. The L_p -difference operator D_p , defined by

$$D_p K = K +_p (-K)$$

for $K \in \mathcal{K}_o^n$, and the identity are $\mathrm{SL}(n)$ equivariant, homogeneous of degree 1 and L_p -Minkowski valuations. We will show that for $n \geq 3$ these are all examples.

For $n = 2$, there are additional examples. For $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_0 + a_i, b_0 + b_i \geq 0$, $i = 1, 2$, define $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}_o^2$ by

$$Z P = a_0 P +_p b_0(-P) +_p \sum^p (a_i E_i +_p b_i(-E_i))$$

for every $P \in \mathcal{P}_o^2$, where the sum is taken over $E_i \in \mathcal{E}_o(P)$. Here \sum^p denotes the L_p -Minkowski sum. Then $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}_o^2$ is $\mathrm{SL}(2)$ equivariant, homogeneous of degree 1, and L_p -Minkowski additive. A further operator is obtained in the following way. Let $\psi_{\pi/2}$ denote the rotation by an angle $\pi/2$ and for $-1 \leq \tau \leq 1$, let $\hat{\Pi}_p^\tau$ be the operator defined in Section 5. Since $\hat{\Pi}_p^\tau$ is $\mathrm{SL}(2)$ contravariant, we have

$$(\psi_{\pi/2} \hat{\Pi}_p^\tau)(\phi P) = \psi_{\pi/2} \phi^{-t} \psi_{\pi/2}^{-1} (\psi_{\pi/2} \hat{\Pi}_p^\tau) P = \phi(\psi_{\pi/2} \hat{\Pi}_p^\tau) P,$$

that is, $\psi_{\pi/2} \hat{\Pi}_p^\tau$ is $\mathrm{SL}(2)$ equivariant. Since $\hat{\Pi}_p^\tau$ is homogeneous of degree $2/p - 1$, an L_p -Minkowski valuation and not continuous, so is $\psi_{\pi/2} \hat{\Pi}_p^\tau$.

The following result is our classification of $\mathrm{SL}(n)$ equivariant L_p -Minkowski valuations. The proof is given in Section 3.

Theorem 1_p. *Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$, $n \geq 3$, be an L_p -Minkowski valuation, $p > 1$, which is $\mathrm{SL}(n)$ equivariant and homogeneous of degree r . If $r = n/p + 1$, then there are constants $a \geq 0$ and $-1 \leq \tau \leq 1$ such that*

$$ZP = a M_p^\tau P$$

for every $P \in \mathcal{P}_o^n$. If $r = 1$, then there are constants $a, b \geq 0$ such that

$$ZP = aP +_p b(-P)$$

for every $P \in \mathcal{P}_o^n$. In all other cases, $ZP = \{o\}$ for every $P \in \mathcal{P}_o^n$.

Let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}_o^2$ be an L_p -Minkowski valuation, $p > 1$, which is $\mathrm{SL}(2)$ equivariant and homogeneous of degree r . If $r = 2/p + 1$, then there are constants $a \geq 0$ and $-1 \leq \tau \leq 1$ such that

$$ZP = a M_p^\tau P$$

for every $P \in \mathcal{P}_o^2$. If $r = 1$, then there are constants $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_0 + a_i, b_0 + b_i \geq 0$, $i = 1, 2$, such that

$$ZP = a_0 P +_p b_0(-P) +_p \sum^p (a_i E_i +_p b_i(-E_i))$$

for every $P \in \mathcal{P}_o^2$, where the sum is taken over $E_i \in \mathcal{E}_o(P)$. If $r = 2/p - 1$, then there are constants $a \geq 0$ and $-1 \leq \tau \leq 1$ such that

$$ZP = a \psi_{\pi/2} \hat{\Pi}_p^\tau P$$

for every $P \in \mathcal{P}_o^2$. In all other cases, $ZP = \{o\}$ for every $P \in \mathcal{P}_o^2$.

As a simple consequence we obtain the following corollary.

Corollary. *If $Z : \mathcal{K}_o^n \rightarrow \mathcal{K}_o^n$, $n \geq 2$, is a continuous, homogeneous, $\mathrm{SL}(n)$ equivariant L_p -Minkowski valuation, $p > 1$, then there are constants $a, b \geq 0$ and $-1 \leq \tau \leq 1$ such that*

$$ZK = a M_p^\tau K \quad \text{or} \quad ZK = aK +_p b(-K)$$

for every $K \in \mathcal{K}_o^n$.

3. PROOF OF THEOREMS 1 AND 1_p

In the following, we work in n -dimensional Euclidean space \mathbb{R}^n with origin o , a fixed orthonormal basis e_1, \dots, e_n , and use coordinates $x = (x_1, \dots, x_n)$ for $x \in \mathbb{R}^n$. An operator $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$ is called *simple*, if $ZP = \{o\}$ for every $P \in \mathcal{P}_o^n$ with $\dim P < n$. Here $\dim P$ is the dimension of the linear hull, $\mathrm{lin} P$, of P . As a first step in the proof, we show that every operator which is $\mathrm{SL}(n)$ equivariant and homogeneous of degree $r \neq 1$ is simple.

Lemma 1. *Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$ be an operator which is $\mathrm{SL}(n)$ equivariant and homogeneous of degree r . Then $ZP \subset \mathrm{lin} P$. If $\dim P \leq (n-1)$ and $r \neq 1$, then $ZP = \{o\}$.*

Proof. Let $P \in \mathcal{P}_o^n$ be such that $\mathrm{lin} P$ is the k -dimensional subspace with equation $x_{k+1} = \dots = x_n = 0$. Since every $P' \in \mathcal{P}_o^n$ with $\dim P' = k$ is a linear image of

such a polytope P and since Z is $\mathrm{SL}(n)$ equivariant, it suffices to prove the lemma in this case. Let

$$\phi = \begin{pmatrix} I & B \\ 0 & A \end{pmatrix},$$

where I is the $k \times k$ identity matrix, 0 is the $(n-k) \times k$ zero matrix, B is an $(n-k) \times k$ matrix, and A is an $(n-k) \times (n-k)$ matrix with determinant 1. Then $\phi \in \mathrm{SL}(n)$ and

$$(2) \quad \phi P = P.$$

Write $x = (x', x'')$ with $x' = (x_1, \dots, x_k)$ and $x'' = (x_{k+1}, \dots, x_n)$ for $x \in \mathbb{R}^n$. Let $x \in ZP$. Since Z is $\mathrm{SL}(n)$ equivariant, (2) implies that $y = \phi x \in ZP$. Therefore

$$(3) \quad \begin{pmatrix} y' \\ y'' \end{pmatrix} = \begin{pmatrix} x' + Bx'' \\ Ax'' \end{pmatrix} \in ZP.$$

This is true for every $(n-k) \times k$ matrix B and every $(n-k) \times (n-k)$ matrix A with determinant 1. If $x'' \neq 0''$, this implies that y' can be an arbitrary vector. Since ZP is bounded, it follows that $x'' = 0''$. Thus $ZP \subset \mathrm{lin} P$.

Now, let $r \neq 1$ and let

$$\phi = \begin{pmatrix} I & 0 \\ 0 & s \end{pmatrix},$$

where I is the $(n-1) \times (n-1)$ identity matrix and $s \geq 0$. Then

$$Z(\phi P) = s^{(r-1)/n} ZP = ZP.$$

Since this holds for every $s \geq 0$ and ZP is bounded, this implies that $ZP = \{o\}$. \square

Next, we show that we can reduce the proof of Theorem 1 to showing that the corresponding results hold for simplices. The arguments used in the proof of the next lemma are well known from several extension theorems for valuations (cf. [9] or [15]).

Lemma 2. *Let $Z_1, Z_2 : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$ be Minkowski valuations. If $Z_1 S = Z_2 S$ for every n -dimensional simplex $S \in \mathcal{P}_o^n$, then $Z_1 = Z_2$.*

Proof. If $T' \in \mathcal{P}_o^n$ is a simplex with $\dim T' = k < n$, then there is a simplex T such that $T' = T \cap H$, where $H = \mathrm{lin} T'$ and such that $T \cap H^+$ and $T \cap H^-$ are both $(k+1)$ -dimensional. Here H^+, H^- denote the closed halfspaces bounded by H . Since Z_i is a valuation, we have for $i = 1, 2$

$$Z_i T + Z_i T' = Z_i(T \cap H^+) + Z_i(T \cap H^-).$$

If $Z_1 S = Z_2 S$ for every $(k+1)$ -dimensional simplex S , this implies that $Z_1 T' = Z_2 T'$. Thus we get by induction that $Z_1 T = Z_2 T$ for every simplex $T \in \mathcal{P}_o^n$.

For $x \in \mathbb{R}^n$ and $i, i = 1, 2$, fixed, $\mu(P) = h(Z_i P, x)$ is a real valued valuation. Let $P \in \mathcal{P}_o^n$ be dissected into n -dimensional polytopes $P_1, \dots, P_m \in \mathcal{P}_o^n$, that is, $P = P_1 \cup \dots \cup P_m$ and the P_i 's have pairwise disjoint interiors. Induction on the dimension and the number of terms shows that the inclusion-exclusion principle

$$(4) \quad \mu(P) = \sum_I (-1)^{|I|-1} \mu(P_I)$$

holds, where the sum is taken over all ordered k -tuples $I = \{i_1, \dots, i_k\}$ such that $1 \leq i_1 < \dots < i_k \leq n$ and $k = 1, \dots, m$. Here $|I|$ denotes the cardinality of I and $P_I = P_{i_1} \cap \dots \cap P_{i_k}$ (cf. [15]).

Let $P \in \mathcal{P}_o^n$. If $\dim P = n$, then we dissect P into n -dimensional simplices $S_i \in \mathcal{P}_n$, $i = 1, \dots, m$. Then (4) implies that $Z_1 P = Z_2 P$. If $\dim P < k$, we use the same argument in $\text{lin } P$. \square

The following lemma is used to prove Theorem 1_p. The proof is same as that of Lemma 2.

Lemma 2_p. *Let $Z_1, Z_2 : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$ be L_p -Minkowski valuations. If $Z_1 S = Z_2 S$ for every n -dimensional simplex $S \in \mathcal{P}_o^n$, then $Z_1 = Z_2$.*

To prove Theorems 1 and 1_p we determine the value of Z for n -dimensional simplices. Since Z is $\text{SL}(n)$ equivariant and homogeneous, it is enough to consider a standard simplex. So let T be the simplex with vertices o, e_1, \dots, e_n .

We start with the planar case.

Proposition 1. *Let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}^2$ be a Minkowski valuation which is $\text{SL}(2)$ equivariant and homogeneous of degree r . If $r = 3$, then there are constants $a_0 \in \mathbb{R}$, $a_1 \geq 0$ such that*

$$ZT = a_0 m(T) + a_1 MT.$$

If $r = 1$, then there are constants $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_i + b_0 + b_1, a_0 + a_2 + b_i \geq 0$, $i = 1, 2$, such that

$$ZT = a_0 T + b_0(-T) + a_1[o, e_1] + b_1[o, -e_1] + a_2[o, e_2] + b_2[o, -e_2].$$

In all other cases, $ZT = \{o\}$.

Proposition 1_p. *Let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}_o^2$ be an L_p -Minkowski valuation, $p > 1$, which is $\text{SL}(2)$ equivariant and homogeneous of degree r . If $r = 2/p + 1$, then there are constants $a \geq 0$ and $-1 \leq \tau \leq 1$ such that*

$$ZT = a M_p^\tau T.$$

If $r = 1$, then there are constants $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_0 + a_i, b_0 + b_i \geq 0$, $i = 1, 2$, such that

$$ZT = a_0 T + b_0(-T) + a_1[o, e_1] + b_1[o, -e_1] + a_2[o, e_2] + b_2[o, -e_2].$$

If $r = 2/p - 1$, then there are constants $a_1, a_2 \geq 0$ such that

$$ZT = [-a_1(e_1 - e_2), a_2(e_1 - e_2)].$$

In all other cases, $ZT = \{o\}$.

Proposition 1 is basically a special case of Proposition 1_p. The only difference is the range of the operators. We prove both propositions at the same time.

Proof. If $p > 1$, let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}_o^2$, and if $p = 1$, let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}^2$.

For $0 < \lambda < 1$, let H_λ be the hyperplane through the origin o with normal vector $(1 - \lambda)e_1 - \lambda e_2$. Then H_λ dissects T into two simplices $T \cap H_\lambda^+$ and $T \cap H_\lambda^-$, where H_λ^+, H_λ^- are the closed halfspaces bounded by H_λ . Since Z is a valuation, we have

$$(5) \quad ZT +_p Z(T \cap H_\lambda) = Z(T \cap H_\lambda^+) +_p Z(T \cap H_\lambda^-).$$

Set $T' = T \cap e_1^\perp$, where e_1^\perp denotes the subspace orthogonal to e_1 , and set

$$(6) \quad \phi_\lambda = \begin{pmatrix} \lambda & 0 \\ 1 - \lambda & 1 \end{pmatrix} \quad \text{and} \quad \psi_\lambda = \begin{pmatrix} 1 & \lambda \\ 0 & 1 - \lambda \end{pmatrix}.$$

Then $T \cap H_\lambda = \psi_\lambda T'$, $T \cap H_\lambda^+ = \phi_\lambda T$, and $T \cap H_\lambda^- = \psi_\lambda T$. Set $q = (r+1)/2$. Since Z is $\text{SL}(2)$ equivariant and homogeneous of degree $2q+1$, (5) implies that

$$(7) \quad ZT +_p (1-\lambda)^q \psi_\lambda ZT' = \lambda^q \phi_\lambda ZT +_p (1-\lambda)^q \psi_\lambda ZT.$$

1. Let $q \neq 0$. By Lemma 1, Z is a simple valuation. Set $f(x) = h^p(ZT, x)$. Then (7) implies that

$$(8) \quad f(x) = \lambda^{p,q} f(\phi_\lambda^t x) + (1-\lambda)^{p,q} f(\psi_\lambda^t x) \quad \text{for } 0 < \lambda < 1, x \in \mathbb{R}^2.$$

We need the following lemma, which is also used for the case $q = 0$.

Lemma 3. *Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ be a function which is positively homogeneous of degree p and for which (8) holds. Then for $x_1 \geq x_2 \geq 0$*

$$(9) \quad f(x_1, x_2) = \frac{x_1^{p,q+p} - x_2^{p,q+p}}{(x_1 - x_2)^{p,q}} f(e_1),$$

$$(10) \quad f(-x_1, -x_2) = \frac{x_1^{p,q+p} - x_2^{p,q+p}}{(x_1 - x_2)^{p,q}} f(-e_1),$$

for $x_2 \geq x_1 \geq 0$

$$(11) \quad f(x_1, x_2) = \frac{x_2^{p,q+p} - x_1^{p,q+p}}{(x_2 - x_1)^{p,q}} f(e_2),$$

$$(12) \quad f(-x_1, -x_2) = \frac{x_2^{p,q+p} - x_1^{p,q+p}}{(x_2 - x_1)^{p,q}} f(-e_2),$$

and for $x_1, x_2 \geq 0$

$$(13) \quad f(-x_1, x_2) = \frac{x_2^{p,q+p}}{(x_1 + x_2)^{p,q}} f(e_2) + \frac{x_1^{p,q+p}}{(x_1 + x_2)^{p,q}} f(-e_1),$$

$$(14) \quad f(x_1, -x_2) = \frac{x_1^{p,q+p}}{(x_1 + x_2)^{p,q}} f(e_1) + \frac{x_2^{p,q+p}}{(x_1 + x_2)^{p,q}} f(-e_2).$$

Proof. The vector e_1 is an eigenvector of ϕ_λ^t with eigenvalue λ , and the vector $e_1 + e_2$ is an eigenvector with eigenvalue 1. The vector e_2 is an eigenvector of ψ_λ^t with eigenvalue $(1-\lambda)$, and the vector $e_1 + e_2$ is an eigenvector with eigenvalue 1. Therefore

$$f(e_1) = \lambda^{p,q} f(\lambda e_1) + (1-\lambda)^{p,q} f(e_1 + \lambda e_2)$$

and

$$f(e_1 + \lambda e_2) = \frac{1 - \lambda^{p,q+p}}{(1-\lambda)^{p,q}} f(e_1).$$

Since f is homogeneous of degree p , this can be written as

$$f(x_1, x_2) = \frac{x_1^{p,q+p} - x_2^{p,q+p}}{(x_1 - x_2)^{p,q}} f(e_1)$$

for $x_1 \geq x_2 \geq 0$. Similarly, (10)–(12) are derived.

From (8) we obtain

$$f(-(1-\lambda)e_1 + \lambda e_2) = \lambda^{p,q+p} f(e_2) + (1-\lambda)^{p,q+p} f(-e_1),$$

which can be written as

$$f(-x_1, x_2) = \frac{x_2^{p,q+p}}{(x_1 + x_2)^{p,q}} f(e_2) + \frac{x_1^{p,q+p}}{(x_1 + x_2)^{p,q}} f(-e_1)$$

for $x_1, x_2 \geq 0$. Similarly, (14) is derived. \square

Let $q > 1/p$. If $f(e_1) \neq 0$, then by Lemma 3

$$\lim_{\lambda \rightarrow 1} f(e_1 + \lambda e_2) = \lim_{\lambda \rightarrow 1} \frac{1 - \lambda^{p q + p}}{(1 - \lambda)^{p q}} f(e_1) = \pm \infty.$$

Since $f(x) = h^p(ZT, x)$ and since ZT is bounded, this is not possible. Thus $f(e_1) = 0$. Similarly, we obtain from Lemma 3 that $f(-e_1) = f(e_2) = f(-e_2) = 0$. Therefore Lemma 3 implies that $f(x) = 0$ for every $x \in \mathbb{R}^2$, that is, $ZT = \{o\}$.

Let $q < 1/p$. Then by Lemma 3 we have

$$\lim_{\lambda \rightarrow 1} f(e_1 + \lambda e_2) = \lim_{\lambda \rightarrow 1} f(-e_1 - \lambda e_2) = 0.$$

Thus $ZT \subset (e_1 + e_2)^\perp$ and there are constants $a_1, a_2 \in \mathbb{R}$ such that

$$f(x) = h^p([-a_1(e_1 - e_2), a_2(e_1 - e_2)], x) \quad \text{for } x \in \mathbb{R}^2.$$

If $p > 1$ and $q = 1/p - 1$, then $a_1, a_2 \geq 0$ and this is just the statement of the proposition. If $q \neq 1/p - 1$, we use (8) with $x = \pm(1, -1)$ and obtain that

$$a_i^p = \lambda^{p q + p} a_i^p + (1 - \lambda)^{p q + p} a_i^p.$$

This implies that $a_1 = a_2 = 0$ and $ZT = \{o\}$.

Let $q = 1/p$. Since $f(x) = h^p(ZT, x)$ is continuous, we obtain from Lemma 3 that $f(e_1) = f(e_2)$ and $f(-e_1) = f(-e_2)$. Thus

$$\begin{aligned} f(x_1, x_2) &= \frac{x_1^{p+1} - x_2^{p+1}}{x_1 - x_2} f(e_1) && \text{for } x_1 \geq x_2 \geq 0, \\ (15) \quad f(-x_1, -x_2) &= \frac{x_1^{p+1} - x_2^{p+1}}{x_1 - x_2} f(-e_1) && \text{for } x_1 \geq x_2 \geq 0, \end{aligned}$$

$$f(-x_1, x_2) = \frac{x_2^{p+1}}{x_1 + x_2} f(e_1) + \frac{x_1^{p+1}}{x_1 + x_2} f(-e_1) \quad \text{for } x_1, x_2 \geq 0$$

and $f(x_1, x_2) = f(x_2, x_1)$. Set $g(x) = \tau h(m(T), x) + h(MT, x)$ with $\tau \in \mathbb{R}$ for $p = 1$ and set $g(x) = h^p(M_p^\tau T, x)$ with $-1 \leq \tau \leq 1$ for $p > 1$. Then a simple calculation shows that

$$\begin{aligned} g(x_1, x_2) &= \frac{(1 + \tau)^p (x_1^{p+1} - x_2^{p+1})}{(p + 1)(p + 2)(x_1 - x_2)} && \text{for } x_1 \geq x_2 \geq 0, \\ (16) \quad g(x_1, x_2) &= \frac{(1 - \tau)^p (x_1^{p+1} - x_2^{p+1})}{(p + 1)(p + 2)(x_1 - x_2)} && \text{for } x_1 \geq x_2 \geq 0, \\ g(x_1, x_2) &= \frac{(1 + \tau)^p x_2^{p+1} + (1 - \tau)^p x_1^{p+1}}{(p + 1)(p + 2)(x_1 + x_2)} && \text{for } x_1, x_2 \geq 0 \end{aligned}$$

and that $g(x_1, x_2) = g(x_2, x_1)$. Comparing this with (15) shows that for $p = 1$

$$f(x) = a_0 h(m(T), x) + a_1 h(MT, x),$$

where $a_0 \in \mathbb{R}$ and $a_1 \geq 0$ are suitable constants, and that for $p > 1$

$$f(x) = a h(M_p^\tau T, x),$$

where $a \geq 0$ and $-1 \leq \tau \leq 1$ are suitable constants.

2. Let $q = 0$. Set $f(x) = h^p(ZT, x) - h^p(ZT', x)$. By Lemma 1, $ZT' \subset e_1^\perp$. Therefore $\phi_\lambda T' = T'$ and (5) implies that

$$f(x) = f(\phi_\lambda^t x) + f(\psi_\lambda^t x) \quad \text{for } 0 < \lambda < 1, x \in \mathbb{R}^2.$$

Thus (8) holds with $q = 0$ and we can apply Lemma 3.

Since $ZT' \subset e_1^\perp$, we have $ZT' = [-s e_2, t e_2]$ with $s, t \in \mathbb{R}$, $-s \leq t$. Note that if $p > 1$, then $h(ZT', \cdot) \geq 0$ and $s, t \geq 0$. Setting $a_0 = f(e_1) + f(e_2)$, $a_1 = -f(e_2)$, $a_2 = -f(e_1) + t^p$ and $b_0 = f(-e_1) + f(-e_2)$, $b_1 = -f(-e_2)$, $b_2 = -f(-e_1) + s^p$, we obtain from Lemma 3 that for $x_1 \geq x_2 \geq 0$

$$\begin{aligned} h^p(ZT, (x_1, x_2)) &= x_1^p(a_0 + a_1) + x_2^p a_2, \\ h^p(ZT, (-x_1, -x_2)) &= x_1^p(b_0 + b_1) + x_2^p b_2, \end{aligned}$$

for $x_2 \geq x_1 \geq 0$

$$\begin{aligned} h^p(ZT, (x_1, x_2)) &= x_1^p a_1 + x_2^p(a_0 + a_2), \\ h^p(ZT, (-x_1, -x_2)) &= x_1^p b_1 + x_2^p(b_0 + b_2), \end{aligned}$$

and for $x_1, x_2 \geq 0$

$$\begin{aligned} h^p(ZT, (-x_1, x_2)) &= x_1^p(b_0 + b_1) + x_2^p(a_0 + a_2), \\ h^p(ZT, (x_1, -x_2)) &= x_1^p(a_0 + a_1) + x_2^p(b_0 + b_2). \end{aligned}$$

As a support function $h(ZT, x)$ is convex. Therefore

$$h(ZT, e_1) + h(ZT, e_2) \geq h(ZT, e_1 + e_2),$$

which implies that $a_0 \geq 0$. Similarly, we obtain $b_0 \geq 0$. If $p > 1$, then $a_0 + a_1, a_0 + a_2, b_0 + b_1, b_0 + b_2 \geq 0$. This is just the statement of the proposition. Since

$$h(ZT, e_1 + e_2) + h(ZT, -e_1 + e_2) \geq 2h(ZT, e_2),$$

we have $a_1 + b_0 + b_1 \geq 0$. Similarly, we obtain $a_2 + b_0 + b_1 \geq 0$ and $a_0 + a_1 + b_1, a_0 + a_1 + b_2 \geq 0$. Thus the proposition holds true. \square

Next, we consider the case $n \geq 3$.

Proposition 2. Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$, $n \geq 3$, be a Minkowski valuation which is $\text{SL}(n)$ equivariant and homogeneous of degree r . If $r = n + 1$, then there are constants $a_0 \in \mathbb{R}$, $a_1 \geq 0$ such that

$$ZT = a_0 m(T) + a_1 MT.$$

If $r = 1$, then there are constants $a, b \geq 0$ such that

$$ZT = aT + b(-T).$$

In all other cases, $ZT = \{o\}$.

Proposition 2_p. Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$, $n \geq 3$, be an L_p -Minkowski valuation, $p > 1$, which is $\text{SL}(n)$ equivariant and homogeneous of degree r . If $r = n/p + 1$, then there are constants $a \geq 0$ and $-1 \leq \tau \leq 1$ such that

$$ZT = aM_p^\tau T.$$

If $r = 1$, then there are constants $a, b \geq 0$ such that

$$ZT = aT +_p b(-T).$$

In all other cases, $ZT = \{o\}$.

We prove both propositions at the same time.

Proof. If $p > 1$, let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$, and if $p = 1$, let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$.

For $0 < \lambda < 1$, $i < j$, let $H_\lambda = H_\lambda(i, j)$ be the hyperplane through o with normal vector $(1 - \lambda)e_i - \lambda e_j$. Then H_λ dissects T into two simplices $T \cap H_\lambda^+$ and $T \cap H_\lambda^-$. Since Z is a valuation, we have

$$(17) \quad ZT +_p Z(T \cap H_\lambda) = Z(T \cap H_\lambda^+) +_p Z(T \cap H_\lambda^-).$$

Define $\phi_\lambda = \phi_\lambda(i, j)$, $\psi_\lambda = \psi_\lambda(i, j)$ by

$$(18) \quad \phi_\lambda e_i = \lambda e_i + (1 - \lambda)e_j, \quad \phi_\lambda e_k = e_k \quad \text{for } k \neq i,$$

$$(19) \quad \psi_\lambda e_j = \lambda e_i + (1 - \lambda)e_j, \quad \psi_\lambda e_k = e_k \quad \text{for } k \neq j.$$

Then $T \cap H_\lambda^+ = \phi_\lambda T$ and $T \cap H_\lambda^- = \psi_\lambda T$. Set $T' = T \cap e_i^\perp$. Then $T \cap H_\lambda = \psi_\lambda T'$. Set $q = (r - 1)/n$. Since Z is $\text{SL}(n)$ equivariant and homogeneous of degree $nq + 1$, (17) implies that

$$(20) \quad ZT +_p (1 - \lambda)^q \psi_\lambda ZT' = \lambda^q \phi_\lambda ZT +_p (1 - \lambda)^q \psi_\lambda ZT.$$

We need the following symmetry relations. Let $i \neq j, k \neq l$ and let $\alpha \in \text{SL}(n)$ be such that $\alpha^t e_i = e_k$, $\alpha^t e_j = e_l$ and $\alpha T = T$. Since Z is $\text{SL}(n)$ equivariant, $ZT = \alpha ZT$. This implies that for $s, t \in \mathbb{R}$

$$(21) \quad h(ZT, s e_i + t e_j) = h(ZT, s e_k + t e_l).$$

1. Let $q \neq 0$. By Lemma 1, Z is a simple valuation. Set $g(x) = h^p(ZT, x)$. Then (20) implies that

$$(22) \quad g(x) = \lambda^{pq} g(\phi_\lambda^t x) + (1 - \lambda)^{pq} g(\psi_\lambda^t x) \quad \text{for } 0 < \lambda < 1, i < j, x \in \mathbb{R}^n.$$

For $k \neq i, j$, we have

$$g(e_k) = \lambda^{pq} g(e_k) + (1 - \lambda)^{pq} g(e_k).$$

Let $q \neq 1/p$. Then this implies that $g(e_k) = 0$. Similarly, we obtain that $g(-e_k) = 0$. Since (22) implies that Lemma 3 holds for $f(s, t) = g(se_i + te_j)$, we obtain that $g(se_i + te_j) = 0$ for $(s, t) \in \mathbb{R}^2$. Combined with the following lemma this shows that $ZT = \{o\}$ for $q \neq 1/p$.

Lemma 4. *Let $g_1, g_2 : \mathbb{R}^n \rightarrow \mathbb{R}$ be functions for which (22) holds. If $g_1(x) = g_2(x)$ for every $x \in \mathbb{R}^n$ where all but two coordinates vanish, then $g_1 = g_2$.*

Proof. Assume that $g_1(x) = g_2(x)$ holds true for every $x \in \mathbb{R}^n$ where at most k , $2 \leq k \leq n - 1$, coordinates are $\neq 0$. We show that then $g_1(x) = g_2(x)$ for every $x \in \mathbb{R}^n$ where at most $(k + 1)$ coordinates are $\neq 0$. So let $x = (x_1, \dots, x_n)$, $n \geq 3$, be such that at most k coordinates are $\neq 0$. Since at least two coordinates of x have the same sign and (22) holds for every pair $i < j$, we may assume that $x_1, x_2 > 0$ or $x_1, x_2 < 0$ and use (22) for $i = 1, j = 2$.

First, let $0 < x_2 < x_1$ or $x_1 < x_2 < 0$. By (22), we have for $0 < \lambda < 1$

$$g_i(\psi_\lambda^{-t} x) = \lambda^{pq} g_i(\phi_\lambda^t \psi_\lambda^{-t} x) + (1 - \lambda)^{pq} g_i(x).$$

Since

$$\psi_\lambda^{-t} x = (x_1, -\frac{\lambda}{1 - \lambda} x_1 - \frac{1}{1 - \lambda} x_2, x_3, \dots, x_n),$$

$$\phi_\lambda^t \psi_\lambda^{-t} x = (x_2, -\frac{\lambda}{1 - \lambda} x_1 - \frac{1}{1 - \lambda} x_2, x_3, \dots, x_n),$$

we set $\lambda = x_2/x_1$ and obtain $0 < \lambda < 1$. In $\psi_\lambda^{-t} x$ and $\phi_\lambda^t \psi_\lambda^{-t} x$ at most k coordinates are $\neq 0$.

Now, let $0 < x_1 < x_2$ or $x_2 < x_1 < 0$. By (22), we have

$$g_i(\phi_\lambda^{-t}x) = \lambda^{p^q} g_i(x) + (1 - \lambda)^{p^q} g_i(\psi_\lambda^t \phi_\lambda^{-t}x).$$

Since

$$\begin{aligned}\phi_\lambda^{-t}x &= \left(\frac{1}{\lambda}x_1 - \frac{1-\lambda}{\lambda}x_2, x_2, \dots, x_n\right), \\ \psi_\lambda^t \phi_\lambda^{-t}x &= \left(\frac{1}{\lambda}x_1 - \frac{1-\lambda}{\lambda}x_2, x_1, x_3, \dots, x_n\right),\end{aligned}$$

we set $\lambda = 1 - x_1/x_2$ and obtain $0 < \lambda < 1$. As before we obtain $g_1(x) = g_2(x)$. In $\phi_\lambda^{-t}x$ and $\psi_\lambda^t \phi_\lambda^{-t}x$ at most k coordinates are $\neq 0$. \square

Let $q = 1/p$. Note that for $x = se_1 + te_2$, $s, t \in \mathbb{R}$, $h(MT, x)$ is a multiple of $h(MT_2, (s, t))$, where T_2 is the 2-dimensional standard simplex, and that corresponding statements hold for $h(m(T), x)$ and $h(M_p^\tau T, x)$. Set $f(s, t) = g(se_1 + te_2)$. Since (22) implies that Lemma 3 holds for $f(s, t) = g(se_1 + te_2)$, we obtain from (15) and (16) that for $p = 1$ and $x = se_1 + te_2$,

$$(23) \quad g(x) = h(ZT, x) = a_0 h(m(T), x) + a_1 h(MT, x),$$

where $a_0 \in \mathbb{R}$ and $a_1 \geq 0$ are suitable constants. Similarly, we obtain that for $p > 1$ and $x = se_1 + te_2$,

$$(24) \quad g(x) = h^p(ZT, x) = a h(M_p^\tau T, x),$$

where $a \geq 0$ and $-1 \leq \tau \leq 1$ are suitable constants. Since Z as well as m, M, M_p^τ are $SL(n)$ equivariant, we obtain from (21) and the same argument applied to m, M, M_p^τ that (23) and (24) hold for every $x \in \mathbb{R}^n$ where all but two coordinates vanish. Thus applying Lemma 4 shows that the propositions hold true for $q = 1/p$.

2. Let $q = 0$. Let $i = 1, j = 2$. Set $g(x) = h^p(ZT, x) - h^p(ZT', x)$. By Lemma 1, $ZT' \subset e_1^\perp$. Therefore $\phi_\lambda T' = T'$ and (17) implies that

$$g(x) = g(\phi_\lambda^t x) + g(\psi_\lambda^t x) \quad \text{for } 0 < \lambda < 1, x \in \mathbb{R}^n.$$

Thus (22) holds with $q = 0$. Set $a = h^p(ZT', e_2)$ and $b = h^p(ZT', -e_2)$. We apply Lemma 3 with $f(x_1, x_2) = h^p(ZT, x) - h^p(ZT', x)$ for $x = x_1 e_1 + x_2 e_2$ and obtain that for $x_1 \geq x_2 \geq 0$

$$(25) \quad \begin{aligned}h^p(ZT, (x_1, x_2, 0, \dots, 0)) &= (x_1^p - x_2^p) f(e_1) + x_2^p a, \\ h^p(ZT, (-x_1, -x_2, 0, \dots, 0)) &= (x_1^p - x_2^p) f(-e_1) + x_2^p b,\end{aligned}$$

for $x_2 \geq x_1 \geq 0$

$$(26) \quad \begin{aligned}h^p(ZT, (x_1, x_2, 0, \dots, 0)) &= (x_2^p - x_1^p) f(e_2) + x_2^p a, \\ h^p(ZT, (-x_1, -x_2, 0, \dots, 0)) &= (x_2^p - x_1^p) f(-e_2) + x_2^p b,\end{aligned}$$

and for $x_1, x_2 \geq 0$

$$(27) \quad \begin{aligned}h^p(ZT, (-x_1, x_2, 0, \dots, 0)) &= x_2^p f(e_2) + x_1^p f(-e_1) + x_2 a, \\ h^p(ZT, (x_1, -x_2, 0, \dots, 0)) &= x_1^p f(e_1) + x_2^p f(-e_2) + x_2 b.\end{aligned}$$

Note that (21), (25), and (26) imply that

$$(28) \quad f(e_1) = f(e_2) + a.$$

Since there is a $\beta \in SL(n)$ such that $\beta e_2 = e_3, \beta e_3 = e_2$, and $\beta T' = T'$ and since Z is $SL(n)$ equivariant, we have

$$(29) \quad h(ZT', e_2) = h(ZT', e_3).$$

Since e_3 and $e_1 + e_2$ are eigenvectors with eigenvalue 1 of ϕ_λ^t and ψ_λ^t , it follows from (20) that

$$(30) \quad h(ZT', e_3) = h(ZT, e_3) \quad \text{and} \quad h(ZT', e_1 + e_2) = h(ZT, e_1 + e_2).$$

By (29), (21), and (30), we obtain

$$a = h^p(ZT', e_2) = h^p(ZT, e_1) = f(e_1)$$

and therefore by (28) that $f(e_2) = 0$. Similarly, we get $b = f(-e_1)$. Thus it follows from (25)–(27) that

$$(31) \quad h^p(ZT, x) = a h^p(T, x) + b h^p(-T, x)$$

for every $x = (x_1, x_2, 0, \dots, 0)$. Since ZT is convex, we have $a, b \geq 0$.

The operators Z and $P \mapsto aP +_p b(-P)$ are $\text{SL}(n)$ equivariant. Therefore (31) holds for every $x \in \mathbb{R}^n$ where all but two coordinates vanish. We apply Lemma 4 with

$$g_1(x) = h^p(ZT, x) - h^p(ZT', x)$$

and

$$g_2(x) = a(h^p(T, x) - h^p(T', x)) + b(h^p(-T, x) - h^p(-T', x))$$

and obtain that for every $x \in \mathbb{R}^n$

$$h^p(ZT, x) = a h^p(T, x) + b h^p(-T, x) + w(x),$$

where

$$w(x) = h^p(ZT', x) - a h^p(T', x) - b h^p(-T', x).$$

We identify e_1^\perp with \mathbb{R}^{n-1} and use induction on the dimension to obtain ZT' . The operator Z restricted to convex polytopes in e_1^\perp is a homogeneous, $\text{SL}(n-1)$ equivariant L_p -Minkowski valuation. Let $n = 3$. Then we obtain from Propositions 1 and 1_p that there are constants such that

$$ZT' = a_1 T' +_p b_1(-T') +_p a_2[o, e_2] +_p b_2[o, -e_2] +_p a_3[o, e_3] +_p b_3[o, -e_3].$$

We have

$$h^p(ZT, e_2 + e_3) = a + w(e_2 + e_3) = h^p(ZT', e_2 + e_3) = a_1 + a_2 + a_3$$

and

$$h^p(ZT, e_1 + e_3) = a + w(e_1 + e_2) = h^p(ZT', e_2) = a_1 + a_2.$$

Thus (21) implies that $a_3 = 0$. Similarly, we obtain $a_2 = b_2 = b_3 = 0$. This shows that $w(x) = 0$ for $n = 3$ and $ZT = aT +_p b(-T)$. Let $n \geq 4$. Then we get by induction that

$$ZT' = aT' +_p b(-T').$$

Therefore $w(x) = 0$ also in this case. Thus $ZT = aT +_p b(-T)$ holds for $n \geq 4$. \square

4. CONTRAVARIANT MINKOWSKI VALUATIONS

In this section, our main result on the classification of $\mathrm{SL}(n)$ contravariant Minkowski valuations is formulated. The most important example is the projection operator $\Pi : \mathcal{K}^n \rightarrow \mathcal{K}^n$. The following transformation rule for Π , which is due to Petty (cf. [5]), shows that Π is $\mathrm{SL}(n)$ contravariant and homogeneous of degree $(n-1)$:

$$\Pi(\phi K) = |\det \phi| \phi^{-t} \Pi K \quad \text{for } \phi \in \mathrm{GL}(n).$$

On \mathcal{P}_o^n we define an additional operator with the same transformation behaviour. Note that for a polytope P , ΠP can be written in the following way (cf. [5]). A vector v is a *scaled facet normal* of P , if v is an outer normal to a facet of P and if the length of v is equal to the $(n-1)$ -dimensional volume of the corresponding facet. Then

$$\Pi P = \sum_{v \in \mathcal{V}(P)} [o, v],$$

where $\mathcal{V}(P)$ is the set of scaled facet normals of P . Define the operator $\Pi_o : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$ by

$$\Pi_o P = \sum_{v \in \mathcal{V}_o(P)} [o, v],$$

where $\mathcal{V}_o(P)$ is the set of scaled facet normals of P that correspond to facets that contain the origin. We set $\Pi_o P = \{o\}$ if P contains the origin in its interior. Note that Π_o is a Minkowski valuation and that it is not continuous. For $a_1 \geq 0$, $a_2, a_3 \in \mathbb{R}$ with $a_1 + a_2 + a_3 \geq 0$, the operator $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$ defined by

$$ZP = a_1 \Pi P + a_2 \Pi_o P + a_3 (-\Pi_o P)$$

is a Minkowski valuation which is $\mathrm{SL}(n)$ contravariant and homogeneous of degree $(n-1)$. As we will see, for $n \geq 3$ these are already all examples of homogeneous, $\mathrm{SL}(n)$ contravariant Minkowski valuations on \mathcal{P}_o^n .

For $n = 2$, we have additional examples. Let $\psi_{\pi/2}$ denote the rotation by an angle $\pi/2$. If $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}^2$ is $\mathrm{SL}(2)$ equivariant, then

$$(\psi_{\pi/2} Z)(\phi P) = \psi_{\pi/2} \phi \psi_{\pi/2}^{-1} (\psi_{\pi/2} Z)P = \phi^{-t} (\psi_{\pi/2} Z)P,$$

that is, $\psi_{\pi/2} Z$ is $\mathrm{SL}(2)$ contravariant. If Z is a Minkowski valuation and homogeneous of degree r , so is $\psi_{\pi/2} Z$. This implies that the rotated versions of the operators from Theorem 1 are homogeneous, $\mathrm{SL}(2)$ contravariant Minkowski valuations.

The following result is our classification of $\mathrm{SL}(n)$ contravariant Minkowski valuations. The proof is given in Section 6.

Theorem 2. *Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$, $n \geq 3$, be a Minkowski valuation which is $\mathrm{SL}(n)$ contravariant and homogeneous of degree r . If $r = n-1$, then there are constants $a_1 \geq 0$, $a_2, a_3 \in \mathbb{R}$ with $a_1 + a_2 + a_3 \geq 0$ such that*

$$ZP = a_1 \Pi P + a_2 \Pi_o P + a_3 (-\Pi_o P)$$

for every $P \in \mathcal{P}_o^n$. In all other cases, $ZP = \{o\}$ for every $P \in \mathcal{P}_o^n$.

Let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}^2$ be a Minkowski valuation which is $\mathrm{SL}(2)$ contravariant and homogeneous of degree r . If $r = 3$, then there are constants $a_0 \in \mathbb{R}$ and $a_1 \geq 0$ such that

$$ZP = \psi_{\pi/2} (a_0 m(P) + a_1 M P)$$

for every $P \in \mathcal{P}_o^2$. If $r = 1$, then there are constants $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_i + b_0 + b_1, a_0 + a_1 + b_i \geq 0$, $i = 1, 2$, such that

$$\mathbf{Z}P = \psi_{\pi/2}(a_0 P + b_0(-P) + \sum (a_i E_i + b_i(-E_i)))$$

for every $P \in \mathcal{P}_o^2$, where the sum is taken over $E_i \in \mathcal{E}_o(P)$. In all other cases, $\mathbf{Z}P = \{o\}$ for every $P \in \mathcal{P}_o^2$.

The following simple consequence of this theorem holds.

Corollary 2.1. *If $\mathbf{Z} : \mathcal{K}_o^n \rightarrow \mathcal{K}^n$, $n \geq 3$, is a continuous, homogeneous, $\mathrm{SL}(n)$ contravariant Minkowski valuation, then there is a constant $a \geq 0$ such that*

$$\mathbf{Z}K = a \Pi K$$

for every $K \in \mathcal{K}_o^n$.

If $\mathbf{Z} : \mathcal{K}_o^2 \rightarrow \mathcal{K}^2$ is a continuous, homogeneous, $\mathrm{SL}(2)$ contravariant Minkowski valuation, then there are constants $a_0 \in \mathbb{R}$ and $a_1, b_1 \geq 0$ such that

$$\mathbf{Z}K = \psi_{\pi/2}(a_0 m(K) + a_1 M K) \quad \text{or} \quad \mathbf{Z}K = \psi_{\pi/2}(a_1 K + b_1(-K))$$

for every $K \in \mathcal{K}_o^2$.

For translation invariant valuations we obtain the following result. The proof is given in Section 7.

Corollary 2.2. *Let $\mathbf{Z} : \mathcal{P}^n \rightarrow \mathcal{K}^n$, $n \geq 2$, be a translation invariant, $\mathrm{SL}(n)$ contravariant Minkowski valuation. Then there is a constant $c \geq 0$ such that $\mathbf{Z} = c\Pi$.*

5. CONTRAVARIANT L_p -MINKOWSKI VALUATIONS

In [25] Lutwak, Yang, and Zhang introduced the L_p -projection operator Π_p and obtained an L_p -version of the Petty projection inequality. For $K \in \mathcal{K}_o^n$ which contain the origin as an interior point, Π_p is defined by

$$h^p(\Pi_p K, v) = c_{n,p} \int_{S^{n-1}} |v \cdot u|^p dS_p(K, u)$$

for $v \in \mathbb{R}^n$, where $c_{n,p}$ is chosen such that $\Pi_p B = B$ for the unit ball B . Here $S_p(K, \cdot)$ is the L_p -surface area measure of K , that is, $S_p(K, \cdot) = h(K, \cdot)^{1-p} S(K, \cdot)$, where $S(K, \cdot)$ is the surface area measure of K . It is proved in [25] that

$$\Pi_p(\phi K) = |\det \phi|^{1/p} \phi^{-t} \Pi_p K \quad \text{for } \phi \in \mathrm{GL}(n).$$

Note that Π_p is an L_p -Minkowski valuation on convex bodies that contain the origin in their interiors and that it is not bounded on \mathcal{K}_o^n . We need the following generalization of this operator. For $-1 \leq \tau \leq 1$ and $K \in \mathcal{K}_o^n$ which contain o as an interior point, define $\Pi_p^\tau K$ by

$$h^p(\Pi_p^\tau K, v) = c_{n,p} \int_{S^{n-1}} (|v \cdot u| + \tau(v \cdot u))^p dS_p(K, u).$$

Then Π_p^τ is an $\mathrm{SL}(n)$ contravariant L_p -Minkowski valuation on convex bodies that contain the origin in their interiors. For $P \in \mathcal{P}_o^n$, set

$$h^p(\hat{\Pi}_p^\tau P, v) = c_{n,p} \int_{S^{n-1} \setminus \omega_o(P)} (|v \cdot u| + \tau(v \cdot u))^p dS_p(P, u),$$

where $\omega_o(P)$ is the set of outer unit normal vectors to facets of P that contain the origin. Note that $\hat{\Pi}_p^\tau$ is bounded but not continuous on \mathcal{K}_o^n and that it is an L_p -Minkowski valuation. As we will show, these operators are the only examples of homogeneous, $\mathrm{SL}(n)$ contravariant L_p -Minkowski valuations for $n \geq 3$. For $n = 2$, the rotated version of the operators from Theorem 1_p are additional examples.

The proof of the following result is given in Section 6.

Theorem 2_p. *Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$, $n \geq 3$, be an L_p -Minkowski valuation, $p > 1$, which is $\mathrm{SL}(n)$ contravariant and homogeneous of degree r . If $r = n/p - 1$, then there are constants $a \geq 0$ and $-1 \leq \tau \leq 1$ such that*

$$ZP = a \hat{\Pi}_p^\tau P$$

for every $P \in \mathcal{P}_o^n$. In all other cases, $ZP = \{o\}$ for every $P \in \mathcal{P}_o^n$.

Let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}^2$ be an L_p -Minkowski valuation, $p > 1$, which is $\mathrm{SL}(2)$ contravariant and homogeneous of degree r . If $r = 2/p + 1$, then there are constants $a \geq 0$ and $-1 \leq \tau \leq 1$ such that

$$ZP = a \psi_{\pi/2} M_p^\tau P$$

for every $P \in \mathcal{P}_o^2$. If $r = 1$, then there are constants $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_0 + a_i, b_0 + b_i \geq 0$, $i = 1, 2$, such that

$$ZP = \psi_{\pi/2} (a_0 P +_p b_0(-P) +_p \sum^p (a_i E_i +_p b_i(-E_i)))$$

for every $P \in \mathcal{P}_o^2$, where the sum is taken over $E_i \in \mathcal{E}_o(P)$. If $r = 2/p - 1$, then there are constants $a \geq 0$ and $-1 \leq \tau \leq 1$ such that

$$ZP = a \hat{\Pi}_p^\tau P$$

for every $P \in \mathcal{P}_o^2$. In all other cases, $ZP = \{o\}$ for every $P \in \mathcal{P}_o^2$.

As a simple consequence we obtain the following result.

Corollary. *If $Z : \mathcal{K}_o^n \rightarrow \mathcal{K}^n$, $n \geq 3$, is a continuous, homogeneous, $\mathrm{SL}(n)$ contravariant L_p -Minkowski valuation, $p > 1$, then*

$$ZK = \{o\}$$

for every $K \in \mathcal{K}_o^n$.

If $Z : \mathcal{K}_o^2 \rightarrow \mathcal{K}^2$ is a continuous, homogeneous, $\mathrm{SL}(2)$ contravariant L_p -Minkowski valuation, $p > 1$, then there are constants $a, b \geq 0$ and $-1 \leq \tau \leq 1$ such that

$$ZK = a \psi_{\pi/2} M_p^\tau K \quad \text{or} \quad ZK = \psi_{\pi/2} (aK +_p b(-K))$$

for every $K \in \mathcal{K}_o^2$.

6. PROOF OF THEOREMS 2 AND 2_p

As a first step in the proof, we show that every operator which is $\mathrm{SL}(n)$ contravariant and homogeneous of degree $r \neq n - 1$ is simple.

Lemma 5. *Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}^n$ be an operator which is $\mathrm{SL}(n)$ contravariant and homogeneous of degree r . If $\dim P < (n - 1)$, then $ZP = \{o\}$. If $\dim P = (n - 1)$, then $ZP \subset (\mathrm{lin} P)^\perp$. If $\dim P = (n - 1)$ and $r \neq n - 1$, then $ZP = \{o\}$.*

Proof. Let $P \in \mathcal{P}_o^n$ be such that $\text{lin } P$ is the k -dimensional subspace with equation $x_{k+1} = \dots = x_n = 0$. Since every $P' \in \mathcal{P}_o^n$ with $\dim P' = k$ is a linear image of such a polytope P and since Z is $\text{SL}(n)$ contravariant, it suffices to prove the lemma in this case. Let

$$\phi = \begin{pmatrix} I & B \\ 0 & A \end{pmatrix},$$

where I is the $k \times k$ identity matrix, 0 is the $(n-k) \times k$ zero matrix, B is an $(n-k) \times k$ matrix, and A is an $(n-k) \times (n-k)$ matrix with determinant 1. Then $\phi \in \text{SL}(n)$,

$$\phi^{-t} = \begin{pmatrix} I & 0 \\ C & A^{-t} \end{pmatrix}$$

with $C = -A^{-t}B^t$, and

$$(32) \quad \phi P = P.$$

Write $x = \begin{pmatrix} x' \\ x'' \end{pmatrix}$ with $x' = (x_1, \dots, x_k)$ and $x'' = (x_{k+1}, \dots, x_n)$ for $x \in \mathbb{R}^n$. Let $x \in ZP$. Since Z is $\text{SL}(n)$ contravariant, (32) implies that $y = \phi^{-t}x \in ZP$, that is,

$$(33) \quad \begin{pmatrix} y' \\ y'' \end{pmatrix} = \begin{pmatrix} x' \\ Cx' + A^{-t}x'' \end{pmatrix} \in ZP.$$

This is true for every $(n-k) \times k$ matrix B and every $(n-k) \times (n-k)$ matrix A with determinant 1. If $x' \neq o'$, this implies that y'' can be an arbitrary vector. Since ZP is bounded, it follows that $x' = o'$. Thus $ZP \subset (\text{lin } P)^\perp$. If $k = (n-1)$ and $q = 1$, this proves the lemma. Let $k < (n-1)$. Then $x' = o'$ and (33) holds for every $(n-k) \times (n-k)$ matrix A with determinant 1. Since ZP is bounded and $(n-k) \geq 2$, this implies that $x'' = o''$. Let $k = (n-1)$, $r \neq n-1$, and let

$$\phi = \begin{pmatrix} I & 0 \\ 0 & s \end{pmatrix},$$

where I is the $(n-1) \times (n-1)$ identity matrix and $s \geq 0$. Then

$$Z(\phi P) = s^{(r-(n-1))/n} ZP = ZP.$$

Since this holds for every $s \geq 0$ and ZP is bounded, this implies that $ZP = \{o\}$. \square

By Lemmas 2 and 2_p, it suffices to determine the value of Z for n -dimensional simplices to prove Theorems 2 and 2_p. Since Z is $\text{SL}(n)$ contravariant and homogeneous, it is enough to determine ZT , where T is the simplex with vertices o, e_1, \dots, e_n .

We start with the planar case.

Proposition 3. *Let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}^2$ be a Minkowski valuation which is $\text{SL}(2)$ contravariant and homogeneous of degree r . If $r = 3$, then there are constants $a_0 \in \mathbb{R}$ and $a_1 \geq 0$ such that*

$$ZT = \psi_{\pi/2}(a_0 m(T) + a_1 MT).$$

If $r = 1$, then there are constants $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_i + b_0 + b_1, a_0 + a_2 + b_i \geq 0$, $i = 1, 2$, such that

$$ZT = \psi_{\pi/2}(a_0 T + b_0(-T) + a_1[o, e_1] + b_1[o, -e_1] + a_2[o, e_2] + b_2[o, -e_2]).$$

In all other cases, $ZT = \{o\}$.

Proposition 3_p. *Let $Z : \mathcal{P}_o^2 \rightarrow \mathcal{K}_o^2$ be an L_p -Minkowski valuation, $p > 1$, which is $\text{SL}(2)$ contravariant and homogeneous of degree r . If $r = 2/p + 1$, then there are constants $a \geq 0$ and $-1 \leq \tau \leq 1$ such that*

$$ZT = a \psi_{\pi/2} M_p^\tau T.$$

If $r = 1$, then there are constants $a_0, b_0 \geq 0$ and $a_i, b_i \in \mathbb{R}$ with $a_0 + a_i, b_0 + b_i \geq 0$, $i = 1, 2$, such that

$$ZT = \psi_{\pi/2} (a_0 T +_p b_0(-T) +_p a_1 [o, e_1] +_p b_1 [o, -e_1] +_p a_2 [o, e_2] +_p b_2 [o, -e_2]).$$

If $r = 2/p - 1$, then there are constants $a_1, a_2 \geq 0$ such that

$$ZT = [-a_1(e_1 + e_2), a_2(e_1 + e_2)].$$

In all other cases, $ZT = \{o\}$.

That these propositions hold true can be seen in the following way. Let Z be as in Proposition 3 or 3_p. Then $\psi_{\pi/2} Z$ is an L_p -Minkowski valuation which is $\text{SL}(2)$ equivariant and homogeneous of degree r . Thus Propositions 1 and 1_p immediately imply that the above propositions hold true.

Next, we consider the case $n \geq 3$.

Proposition 4. *Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$, $n \geq 3$, be a Minkowski valuation, which is $\text{SL}(n)$ contravariant and homogeneous of degree r . If $r = n - 1$, then there are constants $a_1 \geq 0$, $a_2, a_3 \in \mathbb{R}$ with $a_1 + a_2 + a_3 \geq 0$ such that*

$$ZT = a_1 \Pi T + a_2 \Pi_o T + a_3(-\Pi_o T).$$

In all other case, $ZT = \{o\}$.

Proposition 4_p. *Let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$, $n \geq 3$, be an L_p -Minkowski valuation, $p > 1$, which is $\text{SL}(n)$ contravariant and homogeneous of degree r . If $r = n/p - 1$, then there are constants $a_1, a_2 \geq 0$, such that*

$$ZT = [-a_1(e_1 + \dots + e_n), a_2(e_1 + \dots + e_n)].$$

In all other cases, $ZT = \{o\}$.

We prove both propositions at the same time.

Proof. If $p > 1$, let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$, and if $p = 1$, let $Z : \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$.

For $0 < \lambda < 1$, $i < j$, let $H_\lambda = H_\lambda(i, j)$ be the hyperplane through o with normal vector $(1 - \lambda)e_i - \lambda e_j$. Then H_λ dissects T into the two simplices $\phi_\lambda T$ and $\psi_\lambda T$, where ϕ_λ and ψ_λ are defined by (18). Set $T' = T \cap e_i^\perp$. Then $T \cap H_\lambda = \psi_\lambda T'$. Set $q = (r + 1)/n$. Since Z is $\text{SL}(n)$ contravariant, homogeneous of degree $nq - 1$ and an L_p -Minkowski valuation, we have

$$(34) \quad ZT +_p (1 - \lambda)^q \psi_\lambda^{-t} ZT' = \lambda^q \phi_\lambda^{-t} ZT +_p (1 - \lambda)^q \psi_\lambda^{-t} ZT.$$

Denote by $\alpha_{\pi/2} = \alpha_{\pi/2}(i, j)$ the rotation by an angle $\pi/2$ in the plane $\text{lin}\{e_i, e_j\}$, that is,

$$\alpha_{\pi/2} e_i = e_j, \quad \alpha_{\pi/2} e_j = -e_i, \quad \alpha_{\pi/2} e_k = e_k \quad \text{for } k \neq i, j.$$

Then we obtain that

$$(35) \quad (\alpha_{\pi/2} Z)(\phi_\lambda T) = \lambda^{(r+1)/n} \alpha_{\pi/2} \phi_\lambda^{-t} \alpha_{\pi/2}^{-1} (\alpha_{\pi/2} Z)T = \lambda^{(r-1)/n} \phi_\lambda (\alpha_{\pi/2} Z)T$$

and

$$(36) \quad (\alpha_{\pi/2} Z)(\psi_\lambda T) = \lambda^{(r-1)/n} \psi_\lambda (\alpha_{\pi/2} Z)T.$$

1. Let $q \neq 1$. By Lemma 1, Z is a simple valuation. Set $g(x) = h^p(\alpha_{\pi/2} ZT, x)$. Then (34)–(36) imply that

$$(37) \quad g(x) = \lambda^{p^q} g(\phi_\lambda^t x) + (1 - \lambda)^{p^q} g(\psi_\lambda^t x) \quad \text{for } 0 < \lambda < 1, i < j, x \in \mathbb{R}^n.$$

Therefore we have for $k \neq i, j$

$$g(e_k) = \lambda^{p^q} g(e_k) + (1 - \lambda)^{p^q} g(e_k).$$

If $q \neq 1/p$, this implies that $g(e_k) = 0$. Similarly, we obtain that $g(-e_k) = 0$. Since (37) implies that Lemma 3 holds for $f(x_1, x_2) = g(x_1 e_i + x_2 e_j)$, we obtain that $g(x) = 0$ for $x = x_1 e_i + x_2 e_j$. Thus Lemma 4 implies that $ZT = \{o\}$.

If $q = 1/p$, then (37) implies that

$$g(e_i - e_j) = \lambda^{1-p} g(e_i - e_j) + (1 - \lambda)^{1-p} g(e_i - e_j).$$

Therefore $g(e_i - e_j) = 0$. Similarly, we obtain that $g(e_j - e_i) = 0$. Thus we have for $i < j$,

$$ZT \subset (e_i - e_j)^\perp.$$

This shows that $ZT = [-a_1(e_1 + \dots + e_n), a_2(e_1 + \dots + e_n)]$ with suitable constants $a_1, a_2 \geq 0$.

2. Let $q = 1$. Lemma 5 implies that $ZT' \subset \text{lin}\{e_i\}$. Since there is a $\beta \in \text{SL}(n)$ such that $\beta e_i = -e_i$ and $\beta T' = T'$ and since Z is $\text{SL}(n)$ contravariant, we obtain that $ZT' = [-a e_i, a e_i]$ with $a \geq 0$. By (34) we have for $k \neq i, j$

$$h^p(ZT, e_k) + (1 - \lambda)^p h^p(ZT', e_k) = h^p(ZT, e_k) = \lambda^p h^p(ZT, e_k) + (1 - \lambda)^p h^p(ZT, e_k).$$

If $p > 1$, this implies that $h(ZT, e_k) = 0$. Similarly, we obtain that $h(ZT, -e_k) = 0$. Thus $ZT = \{o\}$. So let $p = 1$. Setting $f(x_1, x_2) = h^p(ZT, x) - h^p(ZT', x)$ for $x = x_1 e_i + x_2 e_j$, we see that (37) holds. Therefore we can apply Lemma 3. Since for $i \neq j, k \neq l$ there is an $\alpha \in \text{SL}(n)$ such that $\alpha e_i = e_k, \alpha e_j = e_l$ and $\alpha T = T$ and since Z is $\text{SL}(n)$ contravariant, we see that f does not depend on i, j and that for $x_1, x_2 \in \mathbb{R}$

$$(38) \quad h(ZT, x_1 e_i + x_2 e_j) = h(ZT, x_1 e_k + x_2 e_l).$$

Thus we obtain for $x_1 \geq x_2 \geq 0$

$$\begin{aligned} h(ZT, x_1 e_i - x_2 e_j) &= x_1 (f(e_1) + a) - x_2 f(e_1), \\ h(ZT, -x_1 e_i + x_2 e_j) &= x_1 (f(-e_1) + a) - x_2 f(-e_1), \end{aligned}$$

and for $x_1, x_2 \geq 0$

$$\begin{aligned} h(ZT, x_1 e_i + x_2 e_j) &= x_1 (f(e_1) + a) + x_2 f(e_2), \\ h(ZT, -x_1 e_i - x_2 e_j) &= x_1 (f(-e_1) + a) + x_2 f(-e_2). \end{aligned}$$

It follows from (38) that $f(e_1) + a = f(e_2)$ and $f(-e_1) - a = f(-e_2)$. Setting $a_1 = f(e_1) + f(-e_1) + a, a_2 = -f(-e_1), a_3 = -f(e_1)$ and using (38) shows that

$$(39) \quad h(ZT, x) = a_1 h(\Pi T, x) + a_2 h(\Pi_o T, x) + a_3 h(-\Pi_o T, x)$$

for $x = x_1 e_i + x_2 e_j$. Thus by Lemma 4 the proposition is proved. \square

7. PROOF OF COROLLARIES 1.2 AND 2.2

The main tool is the following result by McMullen.

Theorem ([28]). *Let $\mu : \mathcal{P}^n \rightarrow \mathbb{R}$ be a translation invariant valuation. Then for $s \in \mathbb{Q}$, $s \geq 0$,*

$$\mu(sP) = \sum_{i=0}^n s^i \mu_i(P).$$

The coefficient $\mu_i(P)$ (which is independent of s) is a translation invariant valuation on \mathcal{P}^n , which is homogeneous of degree i .

Let $Z : \mathcal{P}^n \rightarrow \mathcal{K}^n$ be a translation invariant Minkowski valuation. Then for $x \in \mathbb{R}^n$ fixed, $P \mapsto h(ZP, x)$ is a translation invariant real valued valuation. Thus for $s \in \mathbb{Q}$, $s \geq 0$, there is a polynomial expansion

$$h(Z(sP), x) = \sum_{i=0}^n s^i \mu_i(P, x),$$

where for every $x \in \mathbb{R}^n$ the coefficient $\mu_i(\cdot, x)$ is a translation invariant valuation on \mathcal{P}^n , which is homogeneous of degree i .

First, we consider Corollary 1.2, that is, Z is $\mathrm{SL}(n)$ equivariant. Then we have for $\phi \in \mathrm{SL}(n)$, $x \in \mathbb{R}^n$,

$$h(Z(\phi P), x) = \sum_{i=0}^n s^i \mu_i(\phi P, x) = h(ZP, \phi^t x) = \sum_{i=0}^n s^i \mu_i(P, \phi^t x).$$

Thus for $i = 1, \dots, n$,

$$(40) \quad \mu_i(\phi P, x) = \mu_i(P, \phi^t x) \quad \text{for } \phi \in \mathrm{SL}(n), x \in \mathbb{R}^n.$$

Note that a function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ which is homogeneous of degree 1 is the support function of a convex body if and only if f is sublinear, that is, $f(x+y) \leq f(x) + f(y)$ for $x, y \in \mathbb{R}^n$ (cf. [36]). Since $h(Z(sP), \cdot)$ is sublinear for $s > 0$,

$$\mu_n(P, \cdot) = \lim_{s \rightarrow \infty} \frac{h(Z(sP), \cdot)}{s^n}$$

is also sublinear. Thus $\mu_n(P, \cdot)$ is a support function. In view of (40) and the homogeneity of μ_n , we can apply Theorem 1 and obtain that $\mu_n(P, \cdot) = 0$. Therefore

$$h(Z(sP), \cdot) = \sum_{i=0}^{n-1} s^i \mu_i(P, \cdot).$$

Using induction on the degree of homogeneity and the same arguments as above, we obtain that for $i = n-1, \dots, 2$, $\mu_i(P, \cdot)$ is a support function and that by Theorem 1 $\mu_i(P, \cdot) = 0$ for $i = n-1, \dots, 2$. By Lemma 1 we have $Z\{o\} = \{o\}$ and therefore $\mu_0(P, \cdot) = 0$. This implies that $\mu_1(P, \cdot) = h(ZP, \cdot)$. Thus applying Theorem 1 shows that $Z = cD$ with a suitable constant $c \geq 0$ and Corollary 1.2 is proved.

Now, we consider Corollary 2.2, that is, Z is $\mathrm{SL}(n)$ contravariant. Then we have for $i = 1, \dots, n$,

$$(41) \quad \mu_i(\phi P, x) = \mu_i(P, \phi^{-1}x) \quad \text{for } \phi \in \mathrm{SL}(n), x \in \mathbb{R}^n.$$

Since $\mu_n(P, \cdot) = \lim_{s \rightarrow \infty} h(Z(sP), \cdot)/s^n$ is sublinear, it is a support function. In view of (41) and the homogeneity of μ_n , we can apply Theorem 2 and obtain that

$\mu_n(P, \cdot) = 0$. By Lemma 5 we have $Z\{o\} = \{o\}$ and therefore $\mu_0(P, \cdot) = 0$. This implies that

$$h(Z(sP), \cdot) = \sum_{i=1}^{n-1} s^i \mu_i(P, \cdot).$$

Since $\mu_1(P, \cdot) = \lim_{s \rightarrow 0} h(Z(sP), \cdot)/s$ is sublinear, it is a support function. We apply Theorem 2 and obtain that $\mu_1(P, \cdot) = 0$. Using induction on the degree of homogeneity and the same arguments as above, we obtain that for $i = 1, \dots, n-2$, $\mu_i(P, \cdot)$ is also a support function and that by Theorem 2 $\mu_i(P, \cdot) = 0$ for $i = 1, \dots, n-2$. This implies that $h(ZP, \cdot) = \mu_{n-1}(P, \cdot)$. Thus applying Theorem 2 shows that $Z = c\Pi$ with a suitable constant $c \geq 0$ and Corollary 2.2 is proved.

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